

Briefing of Continental Teves Demonstration on Test Track

A TEST VEHICLE DEMONSTRATES AUTONOMOUS DRIVING WITH 2 SURROUNDING MANUALLY DRIVEN CARS

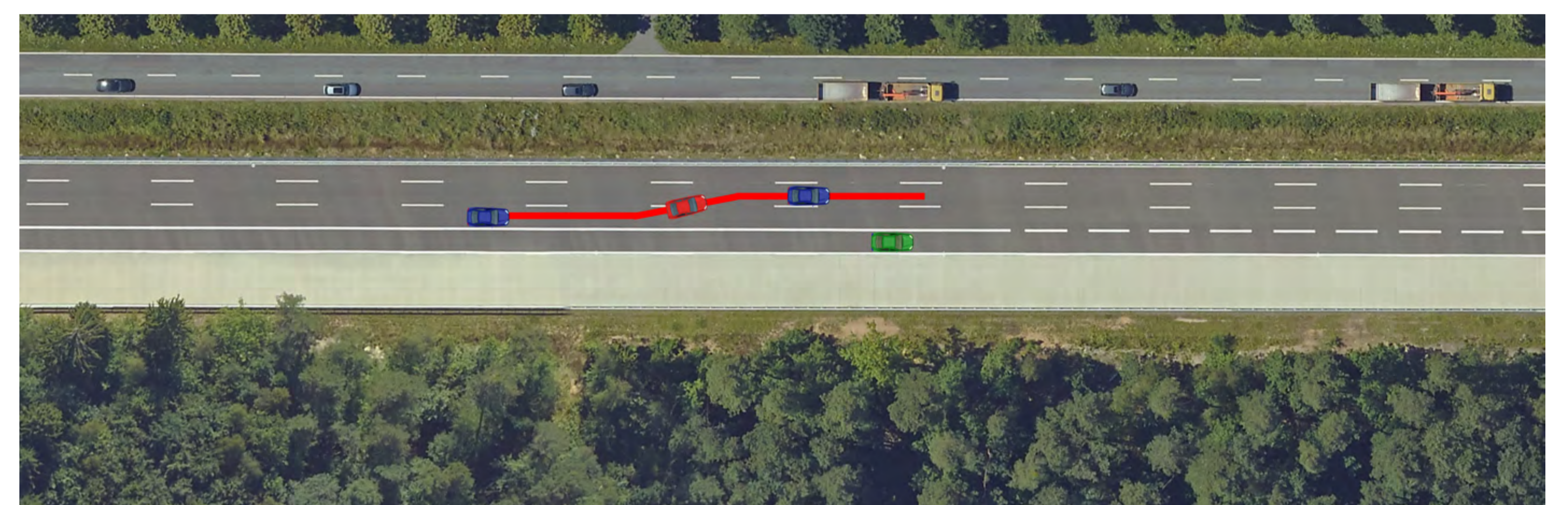
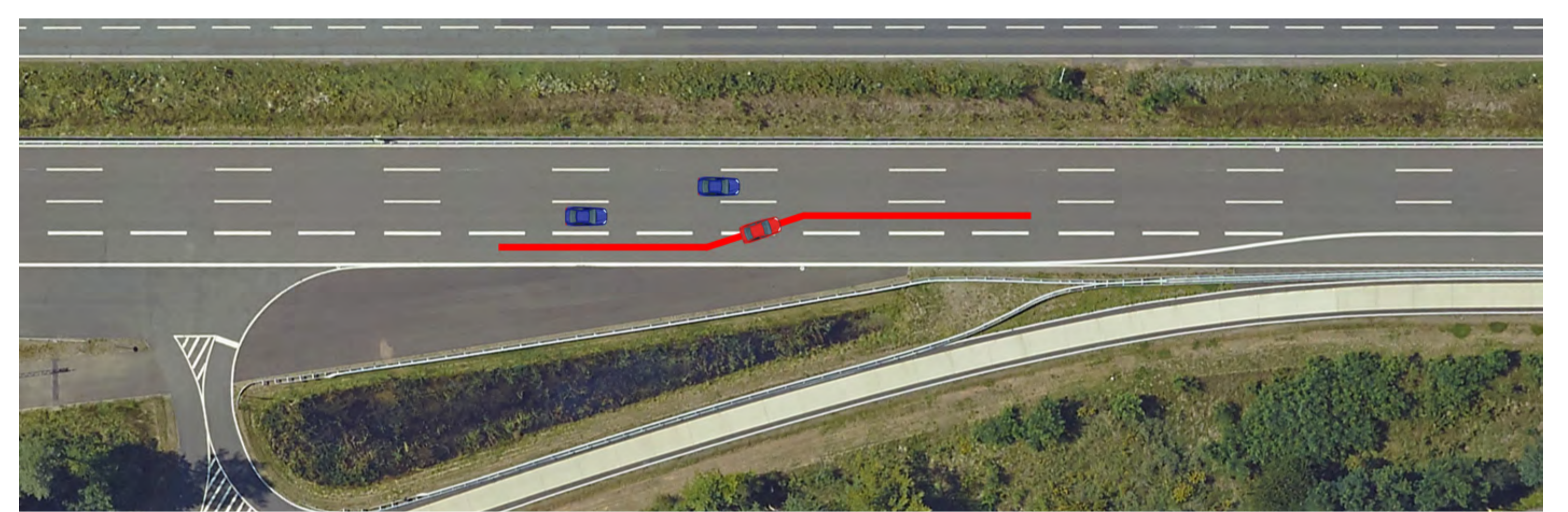
First Round:

- Manual driven Phase in the elevated curve.
- Start of automated driving.

- Your car accelerates a bit in order to enter the Highway in front of a too close car.
- Ko-HAF Safety Server informs your car of presence of a broken down vehicle on shoulder lane.

- Your car starts a strategical maneuver on a breakdown vehicle.

- After the breakdown vehicle, your car drives back to the right most lane. On the Exit lane, your car requests the driver to take the control over.



Second Round:

- Manual driven Phase in the elevated curve.
- Start of automated driving.

- Your car decelerates a bit and changes to the right most lane.
- Ko-HAF Safety Server informs your car of presence of a broken down vehicle on shoulder lane.

- Both rabbits drive away while your car starts a strategical maneuver on a breakdown vehicle.

- Both rabbits simulate a total blockade of the Highway by stopping on their own lane.
- Once the breakdown vehicle is overtaken, your car drives back to the right most lane and prepare for Exit.
- Safety Server informs your car that the Highway is not suitable for autonomous driving anymore.
- Your car triggers a Request To Intervene to the driver.
- The driver does not positively answer to the RTI.
- Your car starts a **Minimal Risk Maneuver**, and therefore decelerates, changes lane to the shoulder lane until it fully stops on the shoulder.
- The driver takes the control again and drives manually to the skidpad's tent.

